# Lower Bound for Sparse Euclidean Spanners * 

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#### Abstract

Given a one-dimensional graph $G$ such that any two consecutive nodes are unit distance away, and such that the minimum number of links between any two nodes (the diameter of $G$ ) is $O(\log n)$, we prove an $\Omega(n \log n / \log \log n)$ lower bound on the sum of lengths of all the edges (i.e., the weight of $G$ ). The problem is a variant of the widely studied partial sum problem. This in turn provides a lower bound on Euclidean spanner graphs with small diameter and low weight, showing that the upper bound from [1] is almost tight.


## 1 Introduction

Given a set of $n$ points $V=\left\{v_{1}, \ldots, v_{n}\right\}$ in $\mathbb{R}^{d}$ and a geometric graph $G=(V, E)$, define the weight of an edge $e=\left(v_{i}, v_{j}\right)$ as $w(e)=\left\|v_{i} v_{j}\right\|$, that is, the Euclidean distance between points $v_{i}$ and $v_{j}$. The weight of a subgraph $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$ is $w\left(G^{\prime}\right)=w\left(E^{\prime}\right)=\sum_{e \in E^{\prime}} w(e)$. The shortest path between nodes $v_{i}$ and $v_{j}$, denoted by $P_{G}\left(v_{i}, v_{j}\right)$, is the smallest-weight path that connects $v_{i}$ and $v_{j}$ in $G$, while the minimum link path, denoted by $\pi\left(v_{i}, v_{j}\right)$, is the one with the smallest number of edges. Define the diameter of the graph as $\Delta(G)=\max _{1 \leq i, j \leq n}\left|\pi\left(v_{i}, v_{j}\right)\right|$.

The problem studied in this paper arises from the study of spanner graphs: a subgraph $G^{\prime} \subseteq G$ is a $t$-spanner of $G$ if for any $v_{i}, v_{j} \in V$,

$$
w\left(P_{G^{\prime}}\left(v_{i}, v_{j}\right)\right) / w\left(P_{G}\left(v_{i}, v_{j}\right)\right) \leq t
$$

Ideally, we would like to have a sparse spanner (i.e., with $O(n)$ edges) with low maximum vertex degree, low weight, and small diameter. Arya et al. [1] investigated the problem of constructing spanners while optimizing various combinations of the above measures simultaneously. For example, they showed that it is possible to construct a spanner with $O(n)$ edges, $O(\log n)$ diameter, and $O(w(\mathcal{T}) \log n)$ weight, where $\mathcal{T}$ is the minimum spanning tree of $G$. The remaining question is then whether this combination is optimal. In other words, we wish to know whether there is a graph so that any spanner of it with $O(\log n)$ diameter has $\Omega(w(\mathcal{T}) \log n)$ weight.

[^0]To answer this question, we focus on the following problem, which is interesting in its own right. For any graph where every node $v_{i}$ lies on the $x$-axis with coordinate $i$, what is the smallest weight it can have for a given diameter? In particular, we provide an $\Omega(n \log n / \log \log n)$ lower bound on the weight of any such graph with $O(\log n)$ diameter, implying that the result of Arya et al. (i.e., $O(n \log n)$ ) is almost tight. (Note that for the type of graphs that we are inspecting, the weight of its minimum spanning tree is $n-1$. So from now on, we simply bound the weight of the graph with respect to $n$.)
Related work. This one-dimensional graph problem is related to the partial sum problem, where given an array of numbers $A[1], \ldots, A[n]$, one would like to construct a data structure of small size so that a partial sum like $S(i, j)=$ $\sum_{i \leq k \leq j} A[k]$ can be computed efficiently. Roughly speaking, the query time there corresponds to the diameter in our case, while the canonical sets usually constructed for the data structures there correspond to the edge set in our graphs. The partial sum problem is a special case of orthogonal range searching, and has been widely studied. We only give a small sample of results here. For static partial-sum problem, the query time is $\Omega(\alpha(n, m))$ if $m$ units of storage is used [4]. Tight bounds for the partial sum problem in a dynamic setting under various models were provided in [3]. The problem has also been studied for multi-dimensional arrays [2].
Notation. Assume from now on that $V=\left\{v_{1}, \ldots, v_{n}\right\}$ is a set of $n$ ordered points in $\mathbb{R}^{1}$ such that any two consecutive points are unit distance apart. A block of nodes $[i: j]$ is defined as $\left\{v_{i}, v_{i+1}, \ldots, v_{j}\right\}$, and $v_{i}$ and $v_{j}$ are referred to as endpoints of the block. Let $\chi\left(v_{k}\right)$ be the covering of a node $v_{k}$, defined as the number of edges that span over $v_{k}$, i.e., the number of edges $\left(v_{i}, v_{j}\right)$ such that $i<k<j$. set $\chi(G)=\max _{v \in V} \chi(v)$. Two edges $\left(v_{i}, v_{j}\right)$ and $\left(v_{k}, v_{l}\right)$ intersect if $i<k<j<l$. A graph is called a stack if it only contains non-intersecting edges. A cluster in a stack graph $G$ is a maximal subgraph $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$ induced by $V^{\prime}=[i: j]$ such that edge $\left(v_{i}, v_{j}\right) \in E^{\prime}$, and no edge in $E \backslash E^{\prime}$ spans over any point in $V^{\prime}$.

## 2 Diameter and Weight

Weight and covering. The following lemma converts the problem of relating $w(G)$ and $\Delta(G)$ into the problem of relating $\chi(G)$ and $\Delta(G)$. Let $\chi(n, \delta)$ denote the smallest covering for a graph with $n$ nodes and diameter at most $\delta$; let
$w(n, \delta)$ denote the weight of such a graph.
LEMMA 2.1. If $\chi(n, \delta) \geq g(n)$ where $g(n)$ is a concave function, then $w(n, \delta)=\bar{\Omega}(n g(n))$.
Proof. Let $G=(V, E)$ be a graph with diameter $\delta$, covering $\chi(n, \delta)$, and weight $w(n, \delta)$. A vertex $v$ is heavy if $\chi(v) \geq$ $g(n) / 6$; otherwise, $v$ is light. Let $V_{h}$ be the set of heavy nodes. We claim that $\left|V_{h}\right| \geq n / 2$, which implies the lemma.

Suppose to the contrary that $\left|V_{h}\right|<n / 2$. Decompose $V_{h}$ into a set of disjoint maximal blocks $B=\left\{B_{1}, \ldots, B_{k}\right\}$, that is, no larger block $B^{\prime} \subseteq V_{h}$ can contain $B_{i}$, for any $1 \leq i \leq k$. By contracting the induced subgraph of each $B_{i}$ into a single node $v_{i}$, for $1 \leq i \leq k$, we obtain a new graph $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$. Obviously, $\left|V^{\prime}\right| \geq n-\left|V_{h}\right| \geq n / 2$, and $\Delta\left(G^{\prime}\right) \leq \Delta(G)=\delta$. Furthermore, we have that $\chi\left(G^{\prime}\right) \leq g(n) / 3$. To see this, first note that all light vertices from $V$ remain light in $V^{\prime}$. For a contracted heavy vertex $v_{i}, \chi\left(v_{i}\right) \leq \chi\left(v_{i}^{-}\right)+\chi\left(v_{i}^{+}\right)$, where $v_{i}^{-}\left(v_{i}^{+}\right)$is the vertex in $V^{\prime}$ to the immediate left (right) of $v_{i}$ along the horizontal line. Since $v_{i}^{-}$and $v_{i}^{+}$are light, $\chi\left(v_{i}\right) \leq g(n) / 3$. We further reduce the size of $V^{\prime}$ to $n / 2$ by contracting the subgraph induced by the first $\left|V^{\prime}\right|-n / 2+1$ vertices into a single node. This produces a graph with $n / 2$ nodes and diameter at most $\delta$, and its covering is at most $C=g(n) / 3$. Since $g(n)$ is a concave function, this leads to a contradiction, as $\chi(n / 2, \delta) \geq g(n / 2) \geq g(n) / 2>C$.
Stack graphs. The next lemma allows us to focus only on the covering and diameter of a stack graph.

Lemma 2.2. For any graph $G=(V, E)$, there is a stack graph $\mathcal{S}=(V, \mathcal{E})$ such that $\chi(\mathcal{S}) \leq \chi(G)$ and $\Delta(\mathcal{S}) \leq$ $(\chi(G)+1) \Delta(G)$.
Proof. Intuitively, in order to obtain a stack graph, we wish to split an edge $e$ if it intersects other edges. However, we have to do it in a way such that we do not introduce new intersections while removing an old one. In particular, given a graph $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$, where $V^{\prime}=[i: j]$ is a block of nodes from $V$, let $\bar{E}^{\prime}=E^{\prime} \backslash\left\{\left(v_{i}, v_{j}\right)\right\}$ if edge $\left(v_{i}, v_{j}\right)$ exists. We now find edge $\bar{e}$ whose left endpoint is leftmost in $\bar{E}^{\prime}$. If there are more than one of such edges, choose the one with the rightmost right endpoint. Let $v_{s}$ be the right endpoint of $\bar{e}$. For each edge $\left(v, v^{\prime}\right) \in \bar{E}^{\prime}$ that covers $v_{s}$, we split it at $v_{s}$ into two new edges $\left(v, v_{s}\right)$ and $\left(v_{s}, v^{\prime}\right)$. After splitting all edges covering $v_{s}$, we obtain a new edge set $\bar{E}^{*}$ where no edge from it covers node $v_{s}$ (see Figure 1]. We repeat this process recursively in the two subgraphs induced by nodes $\left\{v_{i}, \ldots, v_{s}\right\}$ and by $\left\{v_{s}, \ldots, v_{j}\right\}$.

The above process produces a stack graph $\mathcal{S}$ without increasing the covering for any vertex $v \in V$. Furthermore, a split on an edge $e \in E$ happens only if $e$ intersects some edge that covers its left endpoint, and each split removes at least one such intersection. This implies that $\Delta(\mathcal{S}) \leq$ $(\chi(G)+1) \Delta(G)$. We omit the proof from here.

(a)

(b)

Figure 1: Block $[i: j]$ with $\bar{e}$ (the thick edge) and $v_{s}$ (hollow point). Dotted edges intersect $\bar{e}$ in (a) and are split in (b).

We now present the relation between the diameter and covering of stack graphs. It is natural to consider a stack graph $\mathcal{S}=(V, \mathcal{E})$ as a tree $T$ : Each node $\tau$ represents an edge $e_{\tau} \in \mathcal{E}$, and the subtree rooted at $\tau$ consists of all the edges from $\mathcal{E}$ contained in $e_{\tau}$. An edge $e_{1} \in \mathcal{E}$ is a child of edge $e$ if $e_{1} \subset e$ (i.e, $e$ contains $e_{1}$ ) and there is no other edge $e^{\prime} \in \mathcal{E}$ such that $e_{1} \subset e^{\prime} \subset e$. We add an artificial edge connecting nodes $v_{1}$ and $v_{n}$ (if it does not exist), which corresponds to the root of $T$. The depth of $T$ is at most $\chi(\mathcal{S})+1$, and every edge can have at most $2 \Delta(\mathcal{S})$ children. Therefore,

$$
\begin{equation*}
n=|V| \leq(2 \cdot \Delta(\mathcal{S}))^{\chi(\mathcal{S})+2} \tag{2.1}
\end{equation*}
$$

Putting everything together. By (2.1) and Lemma2.2 for any graph $G$ with $n$ nodes, there is a corresponding stack graph $\mathcal{S}$ also with $n$ nodes:

$$
n \leq(2 \cdot \Delta(\mathcal{S}))^{\chi(\mathcal{S})+2} \leq[2 \cdot \Delta(G) \cdot(\chi(G)+1)]^{\chi(G)+1}
$$

Take logarithms on both sides,

$$
\chi(G)+1 \geq \frac{\ln n}{\ln \Delta(G)+\ln (\chi(G)+1)+\ln 2}
$$

Substituting $\Delta(G)=O(\log n)$ in the above inequality we obtain $\chi(G)=\Omega(\log n / \log \log n)$ : Lemma2.1now implies the main result:

THEOREM 2.1. Given any 1-dimensional graph $G$ with unit distance between consecutive nodes and $\Delta(G)=O(\log n)$, $w(G)=\Omega(n \log n / \log \log n)$.
COROLLARY 2.1. There is a graph that any of its t-spanners with diameter $O(\log n)$ has $\Omega(w(\mathcal{T}) \log n / \log \log n)$ weight.

## References

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